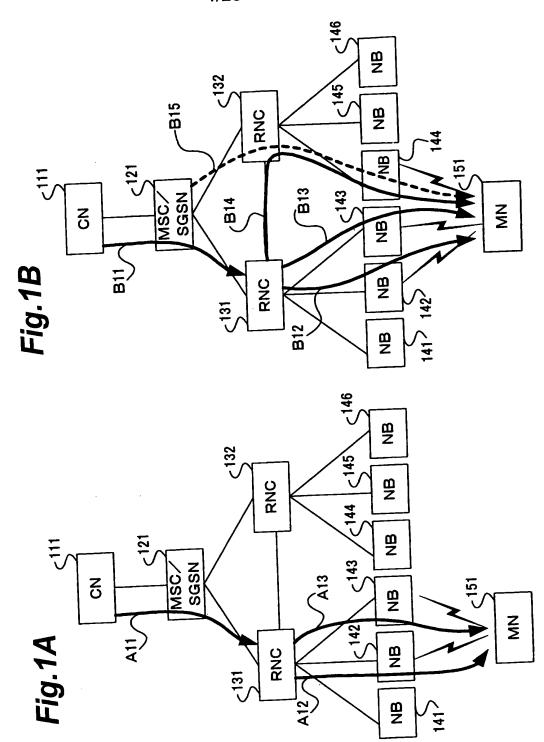
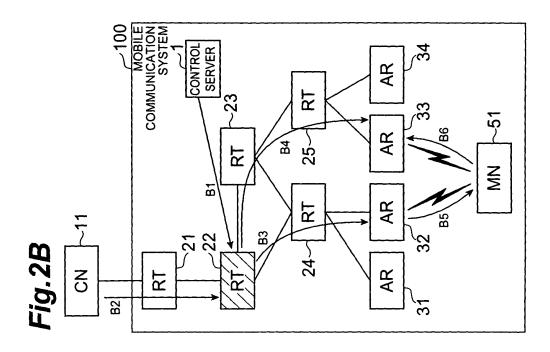
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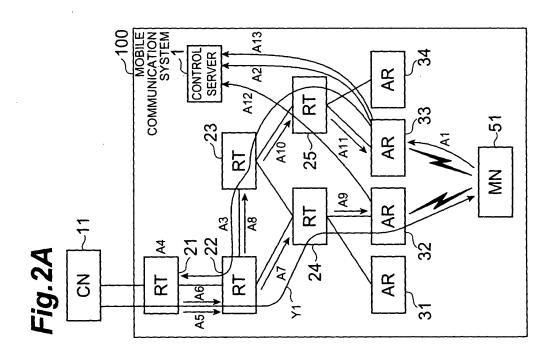


Fig.3

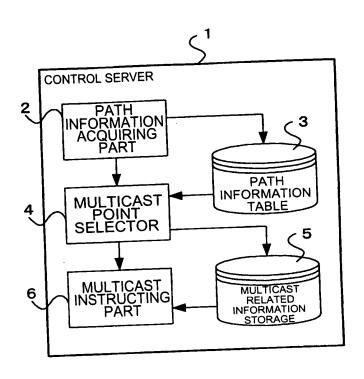
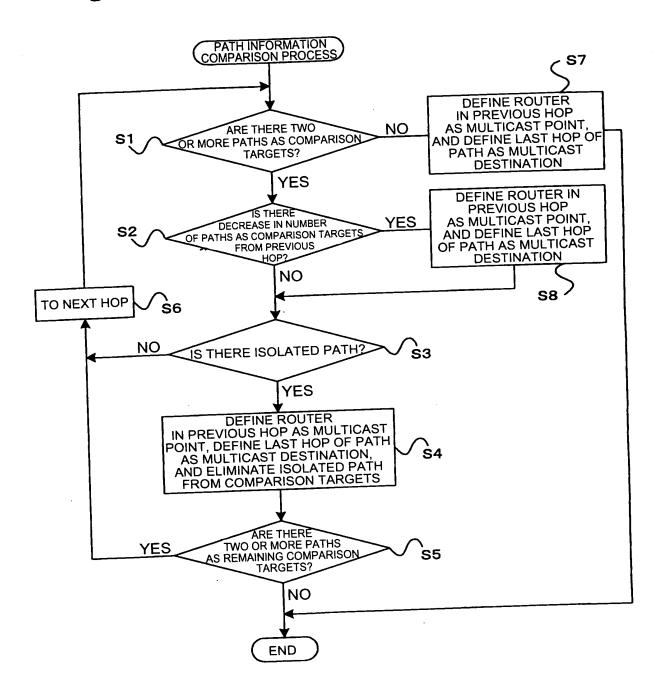


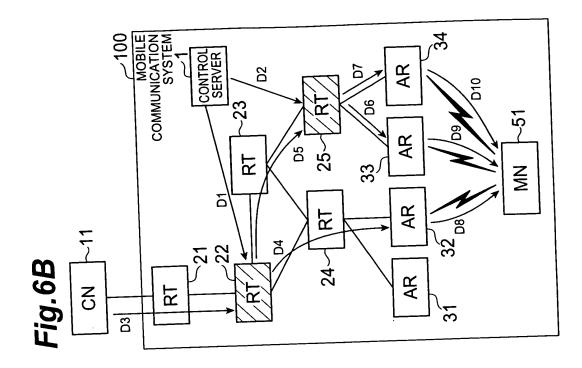
Fig.4

<u>3</u>				
	√ 3a	\(\) \(\)		
	Path 1 (end point: AR32)	Path 2 (end point: AR33)		
1st hop	RT21	RT21		
2nd hop	RT22	RT22		
3rd hop	RT24	RT23		
4th hop	AR32	RT25		
5th hop	_	AR33		

Fig.5



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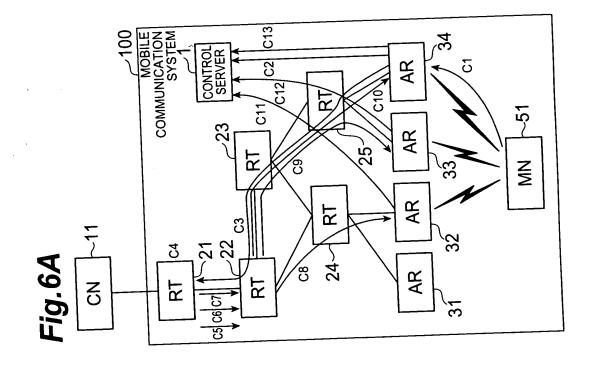
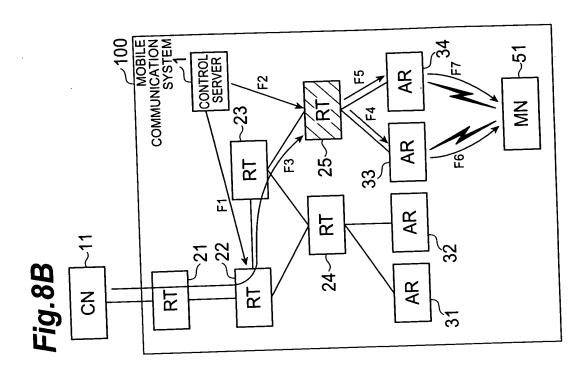


Fig.7

J	3		
	∫ 3a	S ^{3b}	\(\) 3c
	Path 1 (end point: AR32)	Path 2 (end point: AR33)	Path 3 (end point: AR34)
1st hop	RT21	RT21	RT21
2nd hop	RT22	RT22	RT22
3rd hop	RT24	RT23	RT23
4th hop	AR32	RT25	RT25
5th hop	·	AR33	AR34

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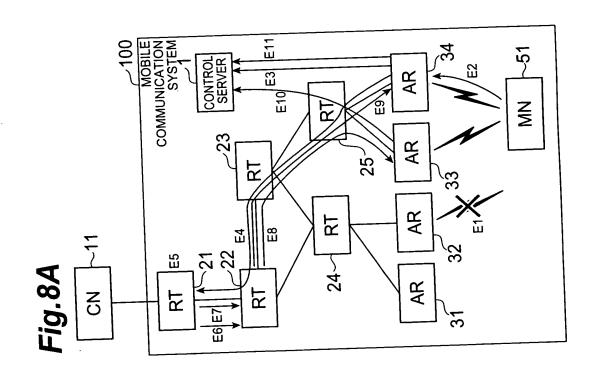
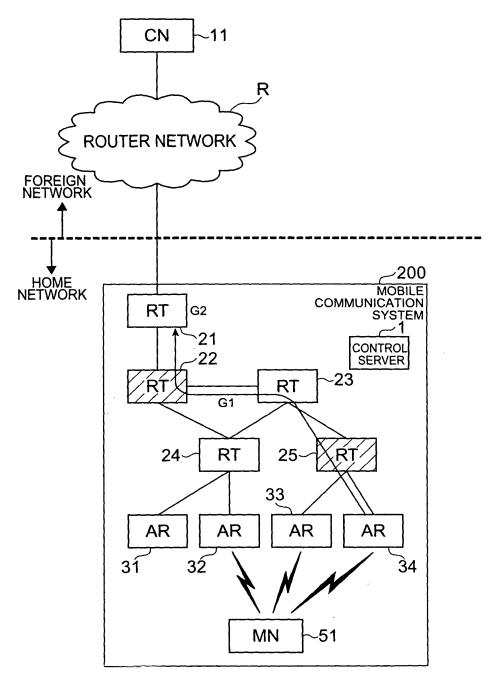


Fig.9

<u>3</u>				
	∠ 3b	\(\) 3c		
	Path 1 (end point: AR33)	Path 2 (end point: AR34)		
1st hop	RT21	RT21		
2nd hop	RT22	RT22		
3rd hop	RT23	RT23		
4th hop	RT25	RT25		
5th hop	AR33	AR34		

Fig.10

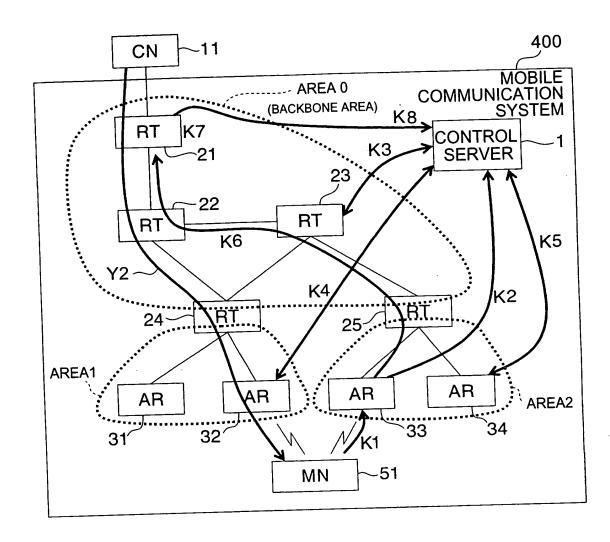


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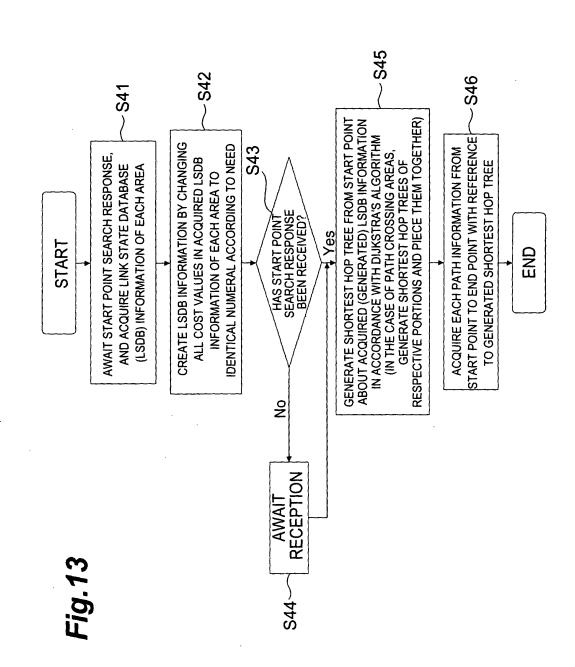
300 MOBILE COMMUNICATION SYSJEM CONTROL SERVER ARS AR R 33 -51 AR Fig.11B Z AR R R

MOBILE COMMUNICATION SYSTEM 꿈 CONTROL SERVER ARR S AR R 5 AR Fig.11A Ζ 32 AR R R

Fig.12



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Fig. 14A

RT25			X10	X11		
RT24		X8	6X			
RT23		X5		9X	X7	
RT22	X2		X3	X4		
RT21		×				
From	RT21	BT22	0T02	151n	RT25	

Fig. 14B

AR32	X15			
AR31	X14			
RT24		X12	X13	
From	RT24	AR31	AR32	

Fig. 14C

		 -	
AR34	X19		
AR33	X18		
RT25		X16	X17
ToFrom	RT25	AR33	AR34

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RT25			-	-	
RT24		-	-		
RT23		-		-	-
RT22	-		-	-	
RT21		-	-		
From	0101	1210	BT23	RT24	RT25

AR32	-			
AR31	-			
RT24		-	-	
From	RT24	AR31	AR32	

AR34	-		
AR33	-		
RT25		1-	-
From	RT25	AR33	AR34

Fia. 15C

Fig.16B Fig.16A **RT24 RT21** AR32 **AR31 RT22 RT23** RT24 Fig.16C RT25 **RT25 AR34**

AR33

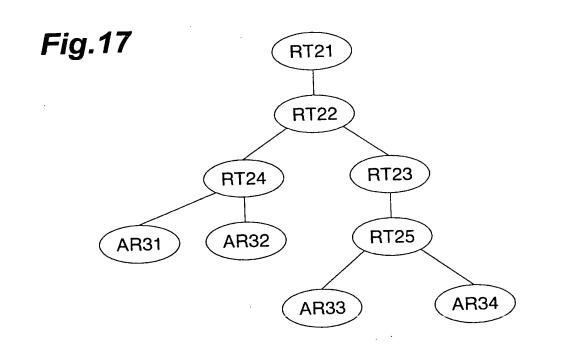


Fig.18

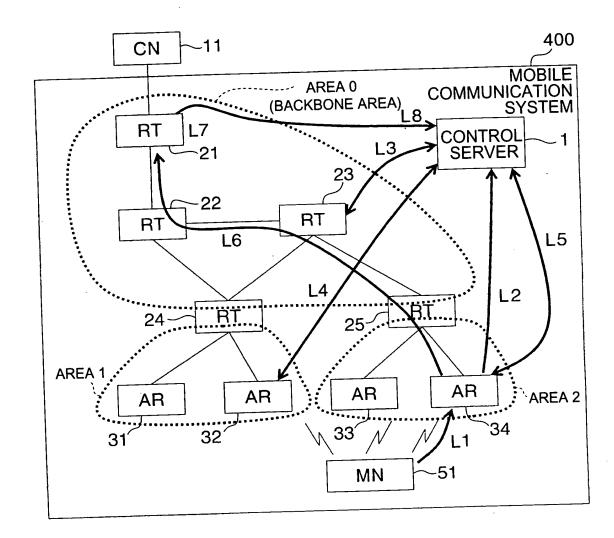


Fig.19

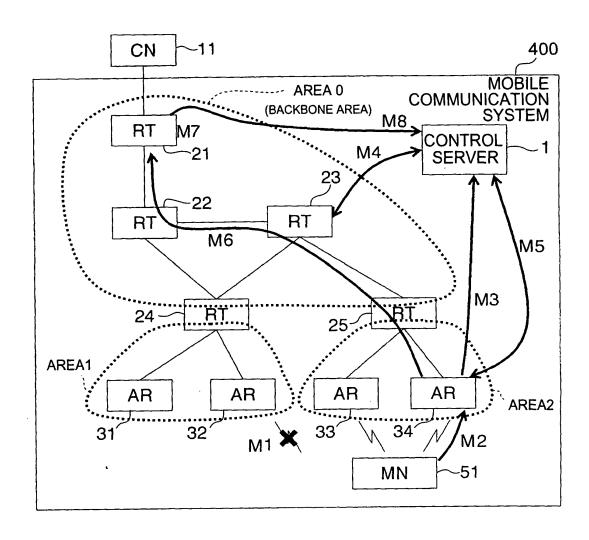


Fig.20

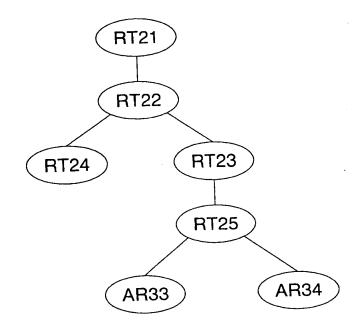
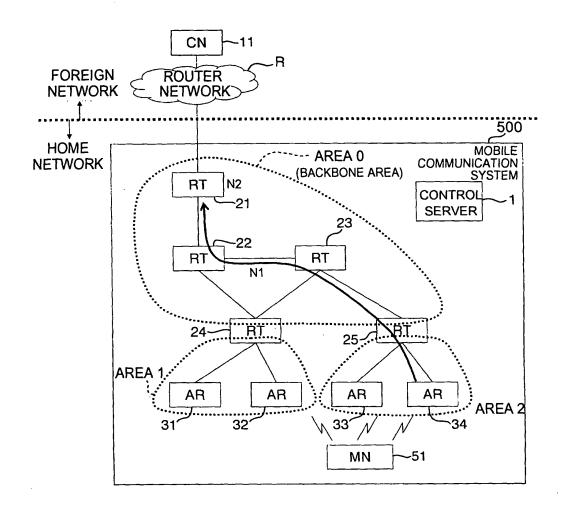
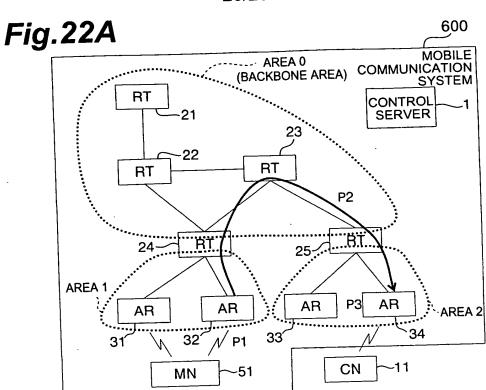


Fig.21



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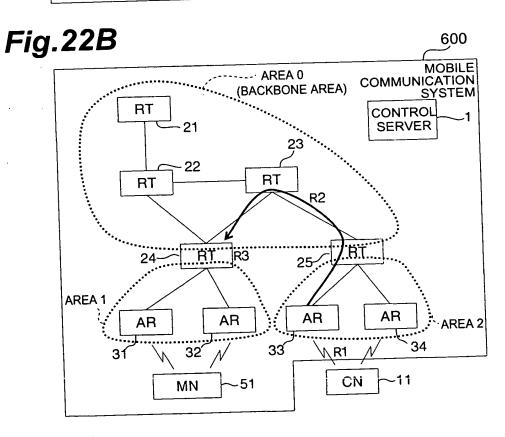


Fig.23A

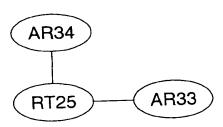


Fig.23C

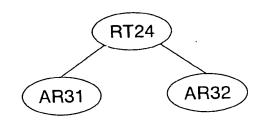


Fig.23B

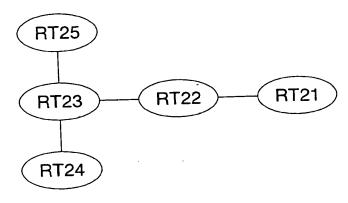
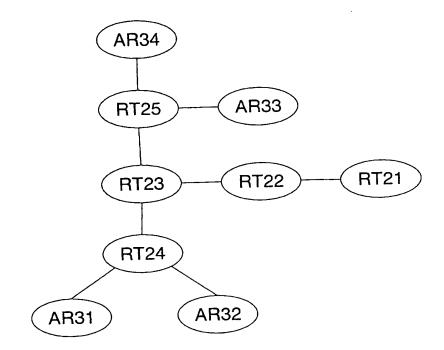


Fig.24



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